

LEAST SQUARES METHODS WITH YULE-WALKER EQUATIONS

- Yule-Walker equations of the form $\begin{bmatrix} \mathbf{R}_B \\ \mathbf{R}_A \end{bmatrix} \mathbf{a} = \begin{bmatrix} \mathbf{c} \\ \mathbf{0} \end{bmatrix}$

are extended to $\begin{bmatrix} \mathbf{R}_B \\ \mathbf{R}_E \end{bmatrix} \mathbf{a} = \begin{bmatrix} \mathbf{c} \\ \mathbf{0} \end{bmatrix}$

where

$$\mathbf{R}_E = \begin{bmatrix} R_x[Q+1] & R_x[Q] & \cdots & R_x[Q-P+1] \\ \vdots & \vdots & \ddots & \vdots \\ R_x[L] & R_x[L-1] & \cdots & R_x[L-P] \end{bmatrix}$$

$$L > P + Q$$

- Lower block is solved by least squares.

LEAST SQUARES YULE-WALKER

The Yule-Walker equations in theory produce

$$\mathbf{R}_E \mathbf{a} = 0$$

but in practice, when estimates are used for \mathbf{R}_E ,

$$\mathbf{R}_E \mathbf{a} = \epsilon$$

Application of least squares results in

$$(\mathbf{R}_E^{*T} \mathbf{R}_E) \mathbf{a} = \begin{bmatrix} \mathcal{S} \\ 0 \end{bmatrix}$$

where \mathcal{S} is the sum of squared errors.

SUGGESTED PROCEDURE

Begin with an order higher than necessary:

$$P' > P \quad \text{and} \quad Q' > Q$$

Follow one of two methods:

- Find an order (P', Q') model of reduced rank.
- Find an order (P, Q) model by averaging techniques.

LS YULE-WALKER METHOD 1

(RANK P ORDER (P', Q') MODEL)

1. P is the “effective rank” of \mathbf{R}_E : $\left(\frac{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_P^2}{\sigma_1^2 + \sigma_2^2 + \dots + \sigma_{P'}^2} \right)^{\frac{1}{2}} \approx 1$

2. With $\mathbf{a} = \begin{bmatrix} 1 \\ \mathbf{a}' \end{bmatrix}$ and $\mathbf{R}_E = \begin{bmatrix} | & \\ \mathbf{r}_0 & \mathbf{R}'_E \\ | & \end{bmatrix}$ \mathbf{a}' is found from

$$\mathbf{a}' = -\mathbf{R}'_E{}^+ \mathbf{r}_0$$

where terms $1/\sigma_k$ for $k > P$ in $\mathbf{R}'_E{}^+$ are set to zero.

3. MA parameters are found in the usual way.

LS YULE-WALKER METHOD 2 (ORDER (P, Q) MODEL)

1. Form submatrices with $P + 1$ columns from \mathbf{R}_E .

Example: $(P' = 2, P = 1)$

$$\begin{bmatrix} R_x[3] & R_x[2] & R_x[1] \\ R_x[4] & R_x[3] & R_x[2] \\ R_x[5] & R_x[4] & R_x[3] \\ R_x[6] & R_x[5] & R_x[4] \end{bmatrix}; \quad \mathbf{R}_{(0)} = \begin{bmatrix} R_x[3] & R_x[2] \\ R_x[4] & R_x[3] \\ R_x[5] & R_x[4] \\ R_x[6] & R_x[5] \end{bmatrix}, \quad \mathbf{R}_{(1)} = \begin{bmatrix} R_x[2] & R_x[1] \\ R_x[3] & R_x[2] \\ R_x[4] & R_x[3] \\ R_x[5] & R_x[4] \end{bmatrix}$$

2. Solve equations of the form

$$\left(\sum_{k=0}^{P'-P} \mathbf{R}_{(k)}^{*T} \mathbf{R}_{(k)} \right) \mathbf{a} = \begin{bmatrix} \mathcal{S} \\ 0 \end{bmatrix}$$

APPLICATION OF METHODS TO DATA

ARMA DATA (Kay, 1988)

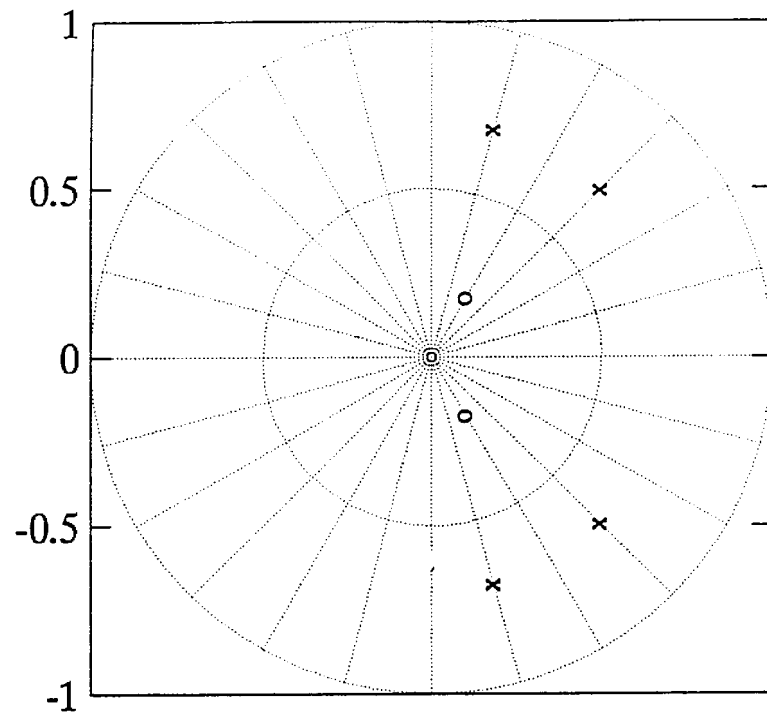
	a_1	a_2	a_3	a_4	b_0	b_1	b_2
ARMA1	-1.352	1.338	-0.662	0.240	1.000	-0.200	0.040
ARMA3	-2.760	3.809	-2.654	0.924	1.000	-0.900	0.810

RECORDED DATA

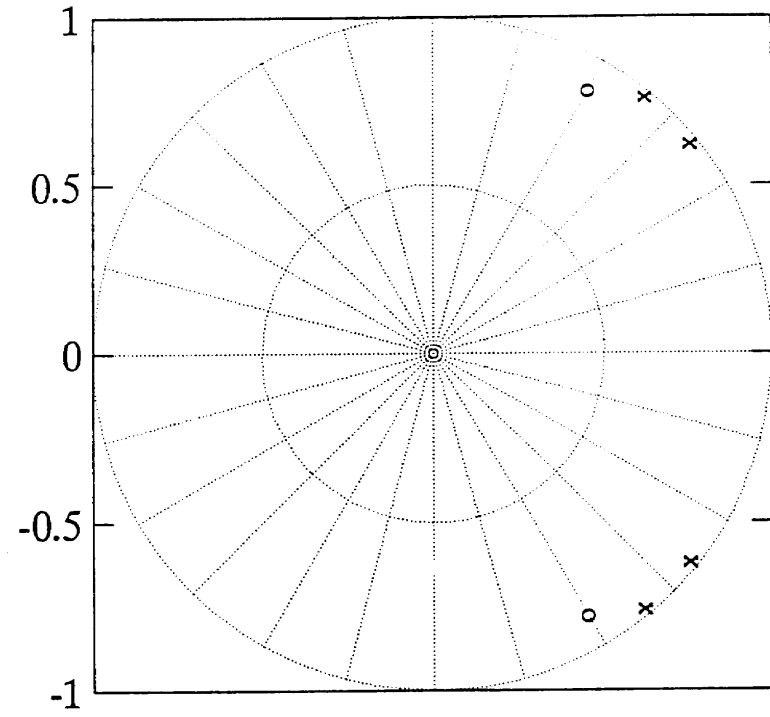
Sound of ruler struck on book.

POLE-ZERO LOCATIONS FOR ARMA DATA

ARMA1

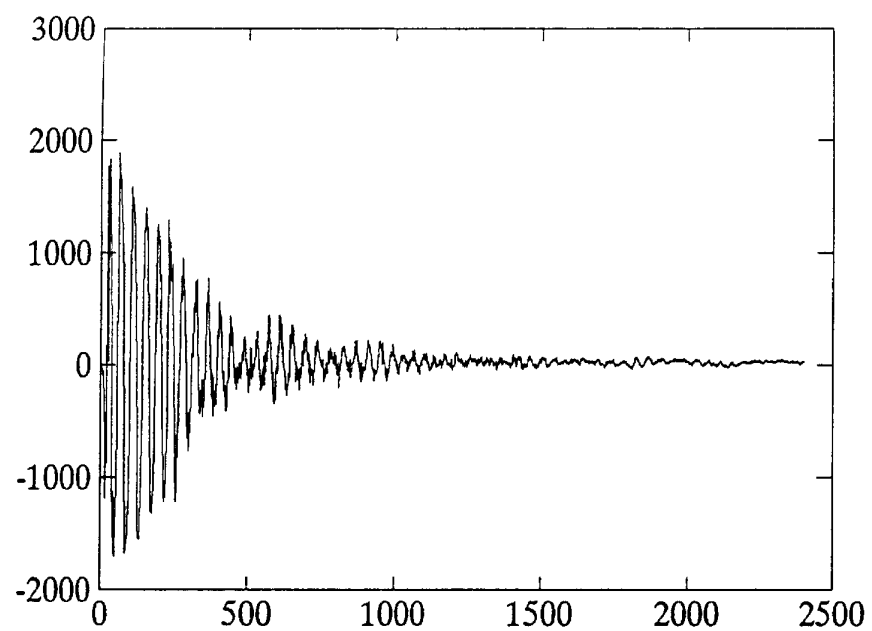


ARMA3

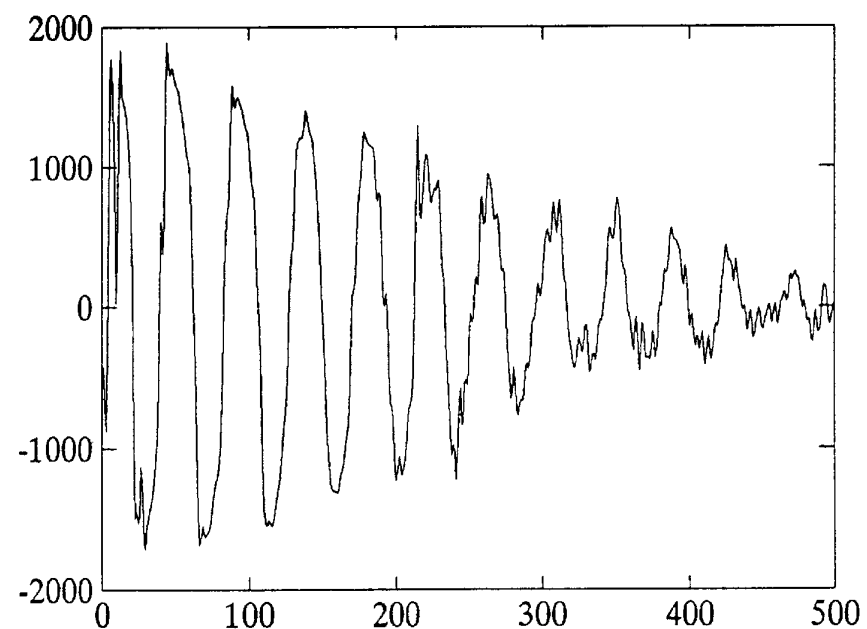


RECORDED RULER DATA

COMPLETE SEQUENCE

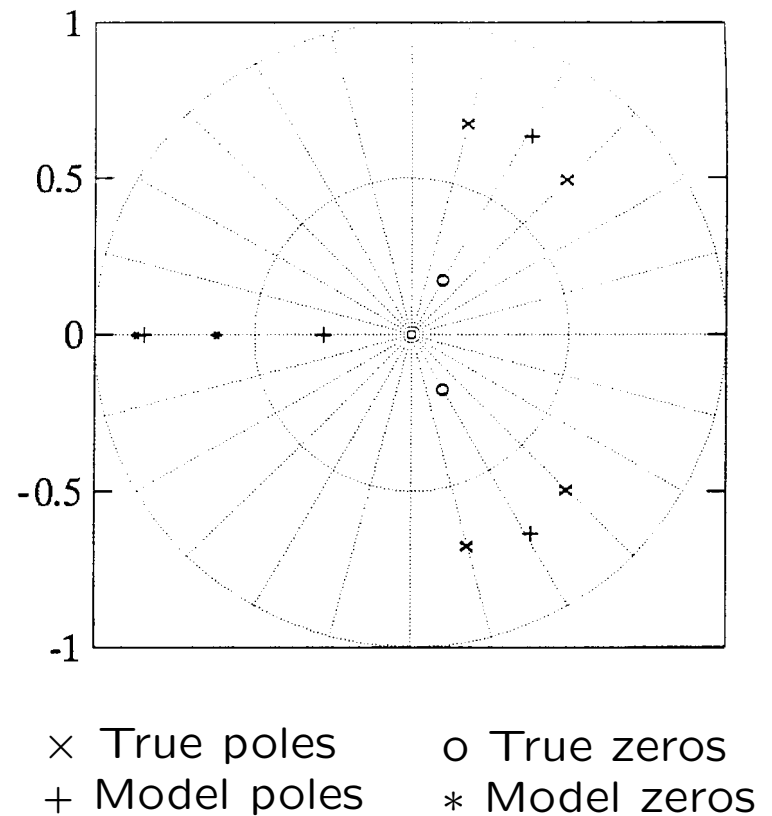
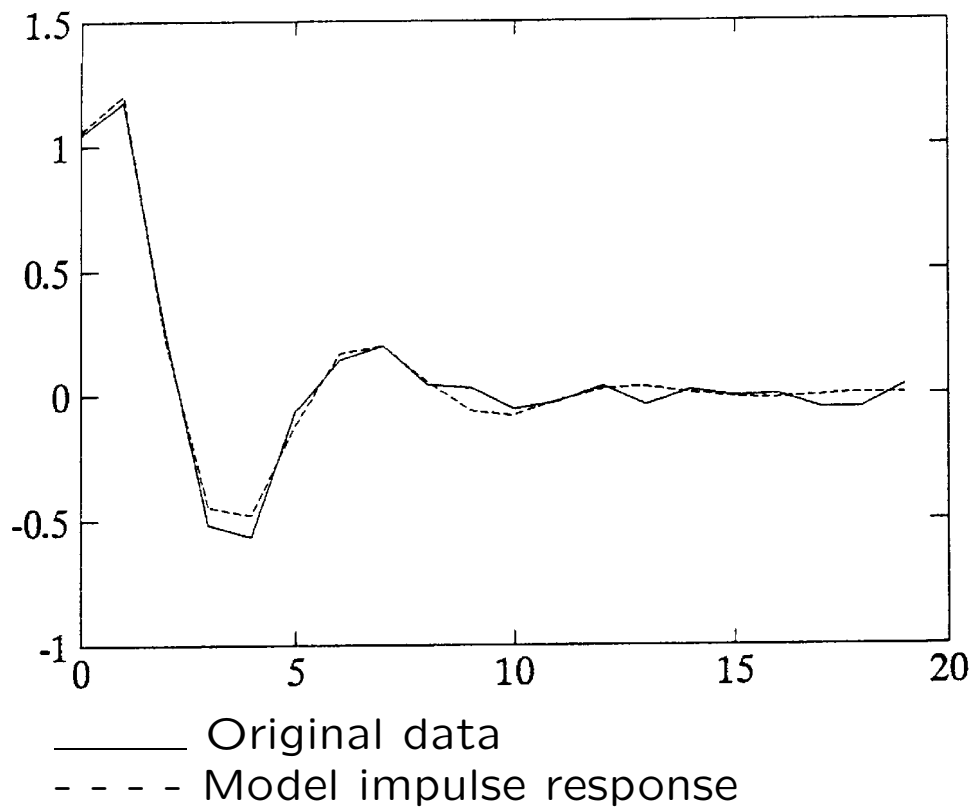


SHORT SEGMENT



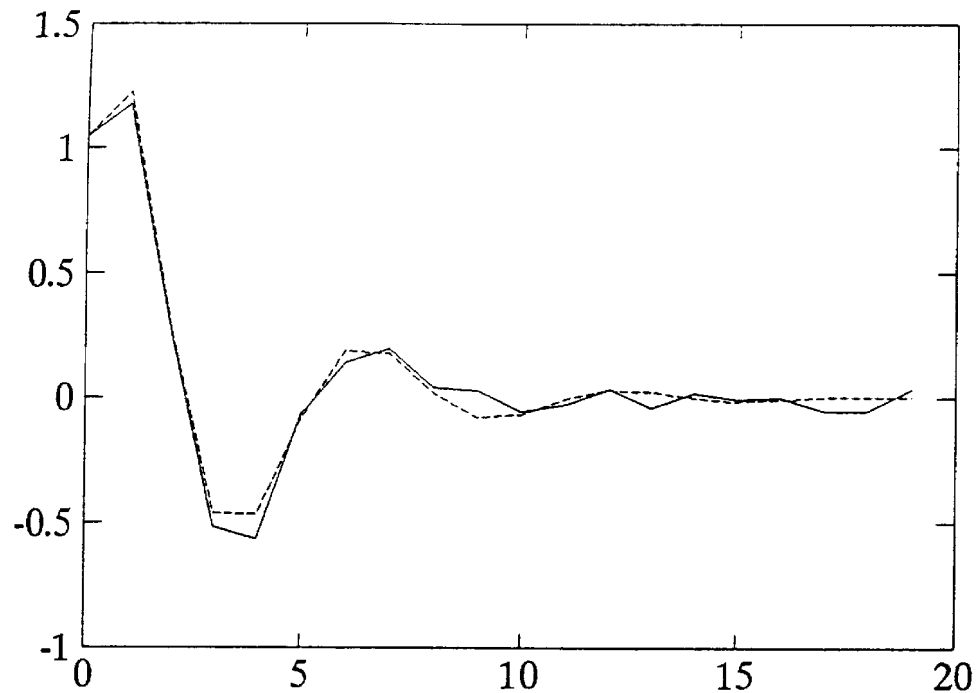
ITERATIVE PREFILTERING: ARMA1 DATA

MODEL ORDER $(P, Q) = (4, 2)$

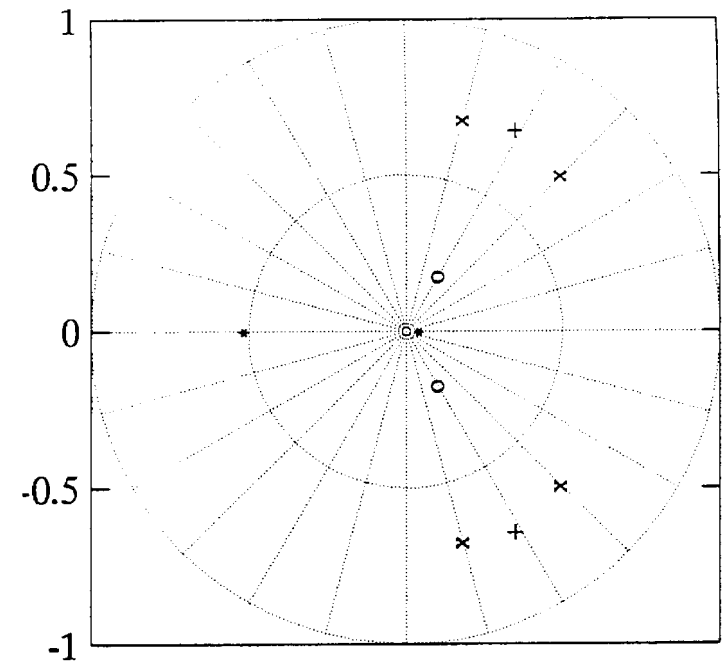


ITERATIVE PREFILTERING: ARMA1 DATA

REDUCED MODEL ORDER $(P, Q) = (2, 2)$



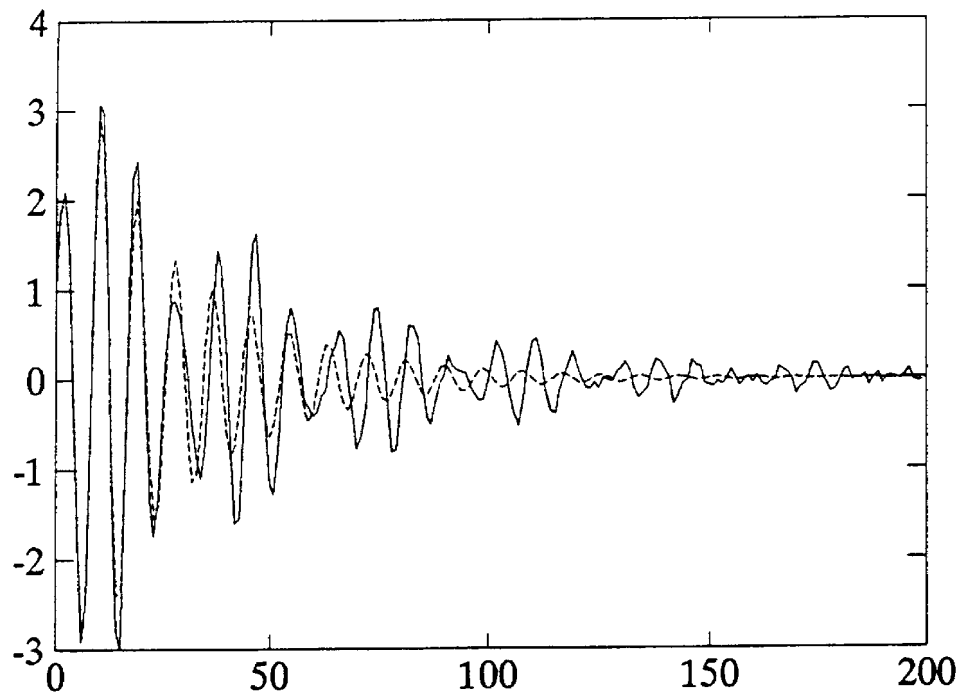
—— Original data
- - - - Model impulse response



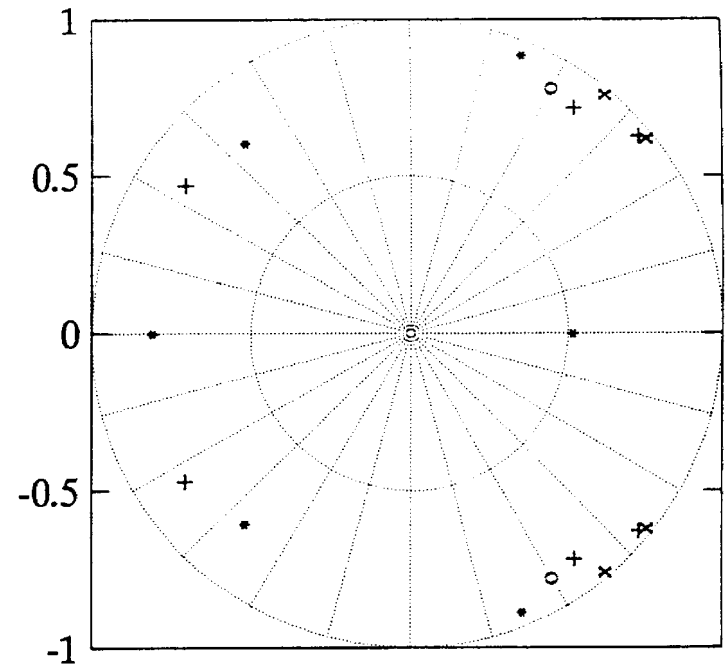
× True poles o True zeros
+ Model poles * Model zeros

PRONY'S METHOD: ARMA3 DATA

MODEL ORDER $(P, Q) = (6, 6)$

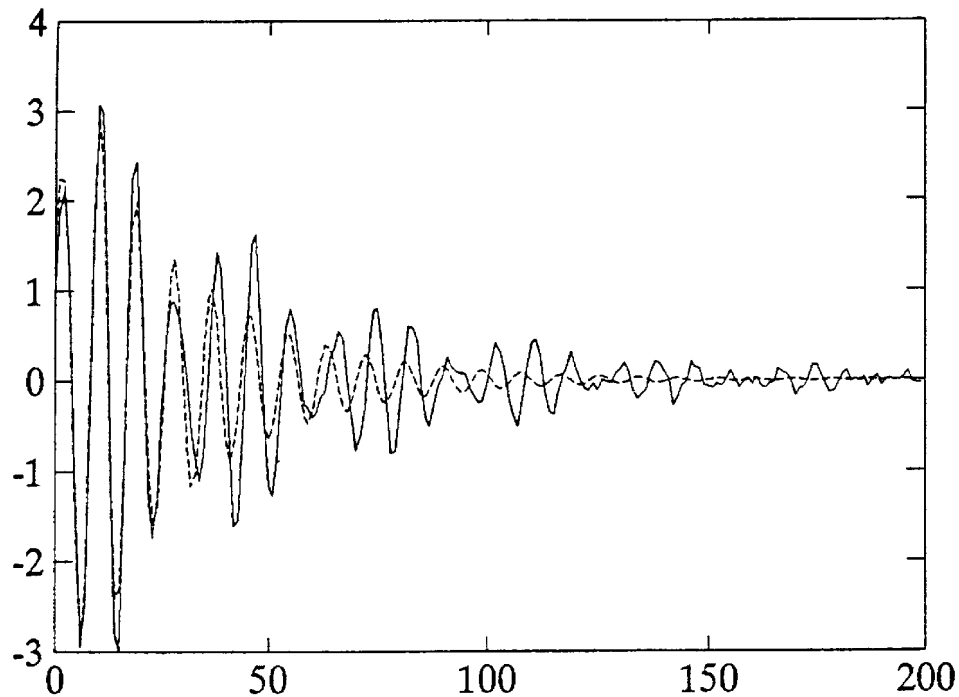


— Original data
- - - Model impulse response

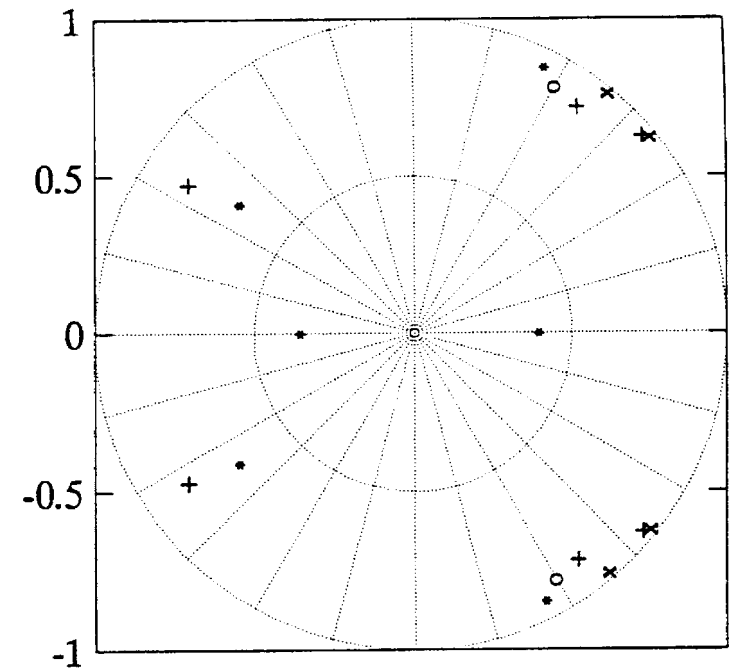


x True poles o True zeros
+ Model poles * Model zeros

PRONY'S METHOD: ARMA3 DATA DURBIN'S METHOD USED TO FIND ZEROS



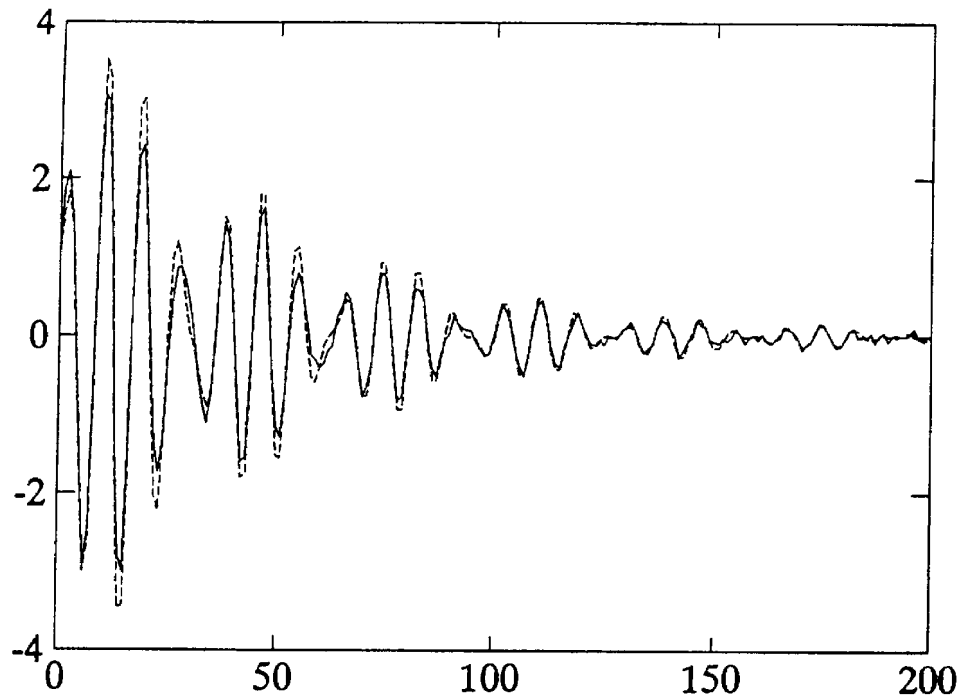
—— Original data
- - - - Model impulse response



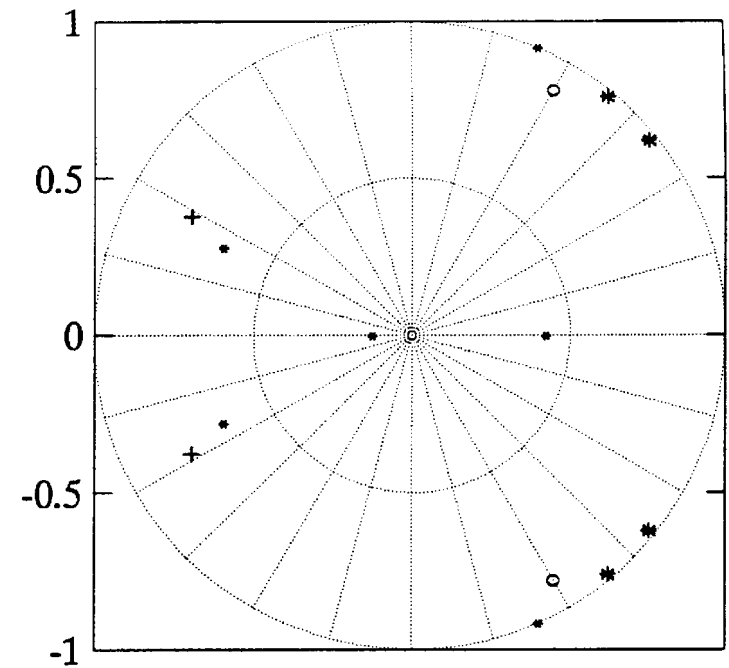
× True poles o True zeros
+ Model poles * Model zeros

LEAST SQUARES YULE-WALKER: ARMA3

MODEL ORDER $(P, Q) = (6, 6)$

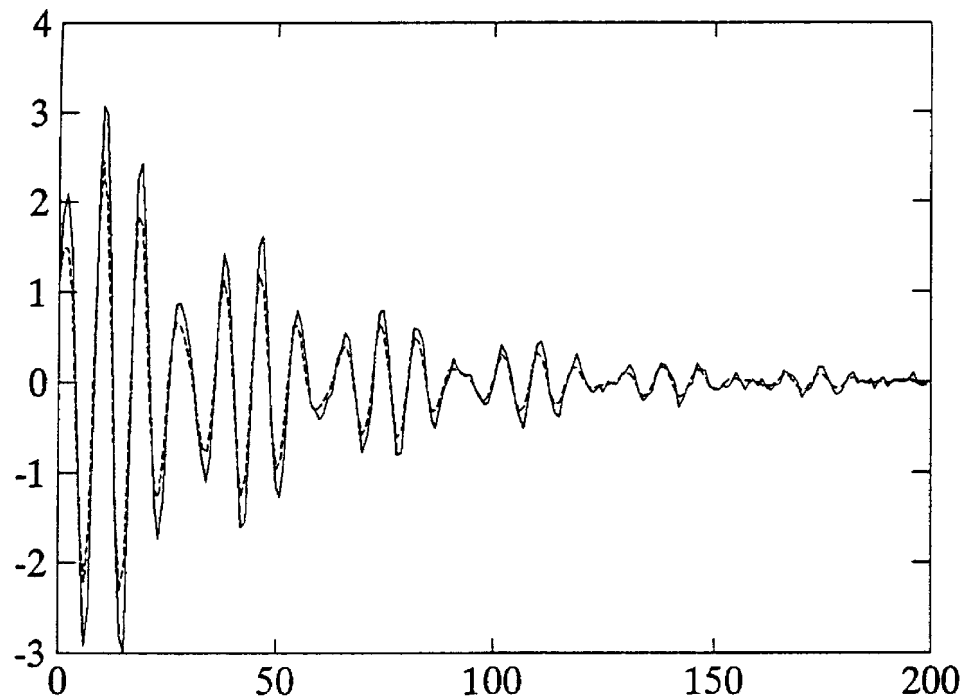


—— Original data
- - - - Model impulse response

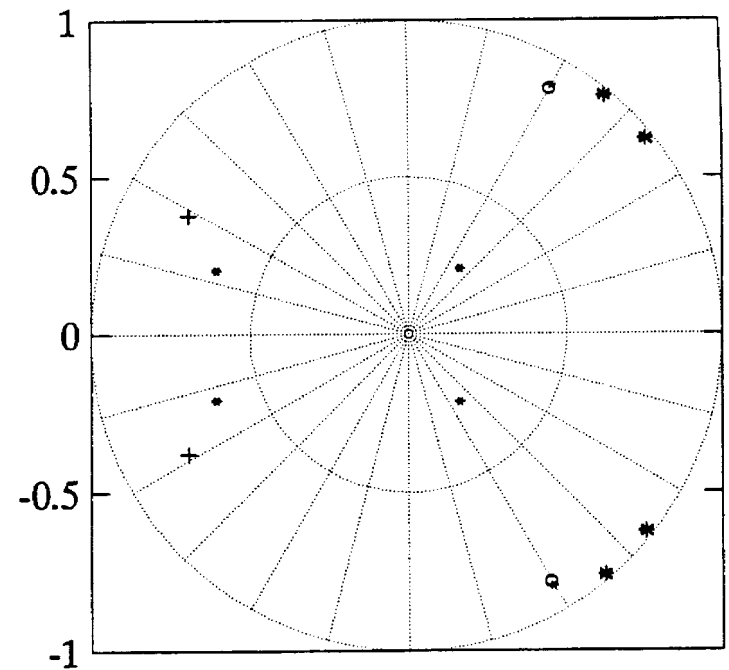


× True poles o True zeros
+ Model poles * Model zeros

LEAST SQUARES YULE-WALKER: ARMA3 DURBIN'S METHOD USED TO FIND ZEROS



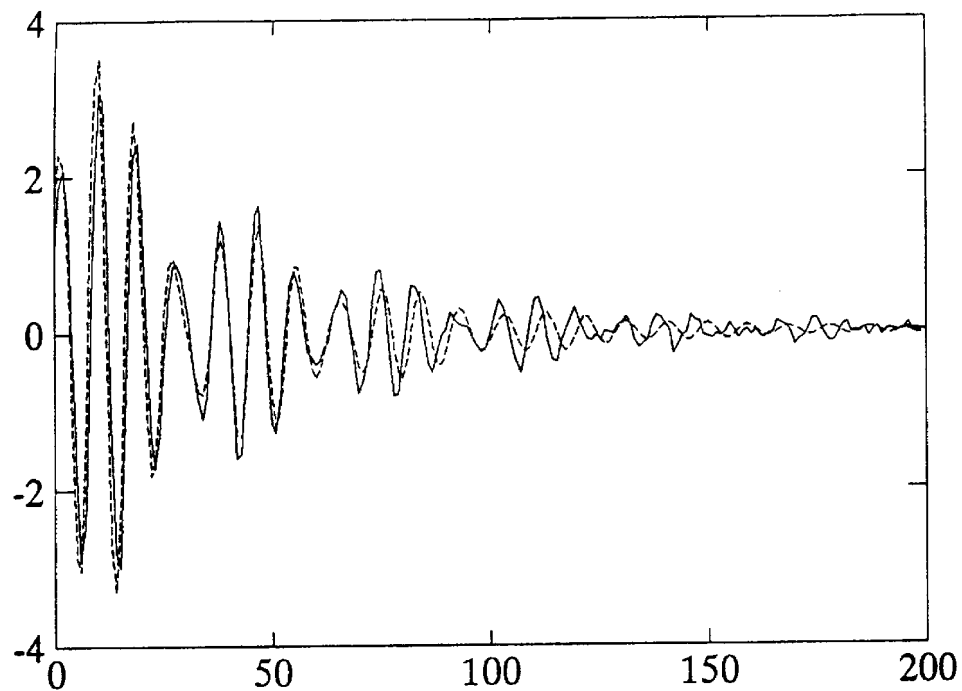
—— Original data
- - - - Model impulse response



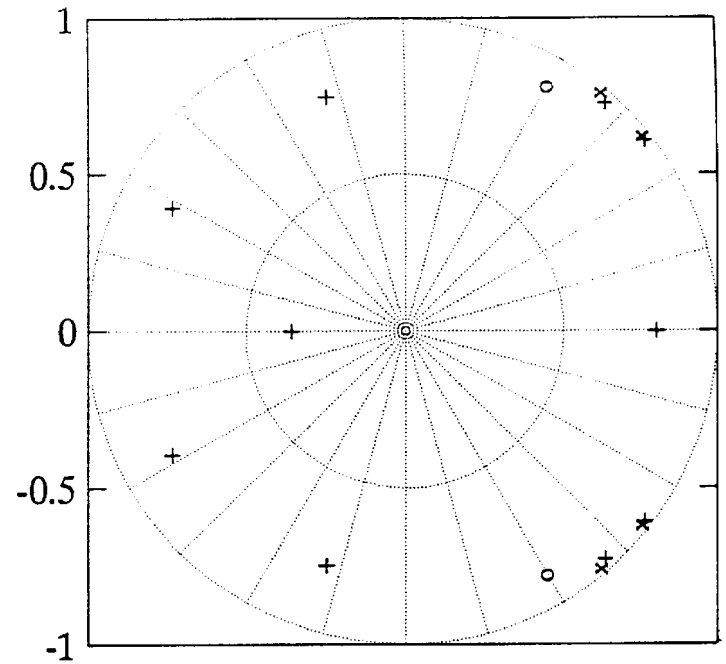
× True poles o True zeros
+ Model poles * Model zeros

COVARIANCE METHOD: ARMA3 DATA

AR MODEL ORDER $P = 10$



— Original data
- - - Model impulse response



× True poles o True zeros
+ Model poles

LEAST SQUARES YULE-WALKER: RULER DATA SHANKS' METHOD USED TO FIND ZEROS

MODEL ORDER $(P, Q) = (6, 16)$

